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TECHNICAL NOTE

AN OPERATIONAL DECISION MODEL EMPLOYING OPERATIONAL AND ENVIRONMENTAL FACTORS

U. S. Department of Commerce

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AN OPERATIONAL DECISION MODEL EMPLOYING OPERATIONAL AND ENVIRONMENTAL FACTORS

I. Introduction

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The meteorologist engaged in operational forecasting is constantly striving to improve his forecast. Nevertheless, the ultimate in forecasting skill, that of predicting all future meteorological events exactly correct, is beyond him now and will emain beyond his reach in the foreseeable future. Thus, in all weather forecasts there will remain a certain degree of uncertainty. Whether this uncertainty is a hindrance to the user of the weather information or not is highly dependent upon the type of activity being planned and, consequently, in most cases is quite variable. The thesis of this Technical Note is the demonstration of a means which will provide a measure of the degree of usefulness of meteorological information under various situations.

The measure of the usefulness and also the effectiveness of weather information can be determined by applying well-known rules of decision theory to operational situations which are affected in some way by meteorological phenomena. This approach is not new and an excellent historical development can be found in a paper by Glahn [1]. The pioneering efforts of Glahn did not go unnoticed. Cummings [2] pointed out the value and need of such an approach. Subsequently, Huschke and Rapp [3] performed a similar analysis of a broadscale, relatively-complex, military operation. In another study Huschke [4] discussed the use of meteorological decision theory in planning requirements and specifications of weapons systems. Rapp [5] developed a simple model to stress the usefulness of weather information in activities ranging from the simplest to the most complex.

The information to be gained from analyses such as those mentioned above is invaluable to the decision-maker. In the same respect, the AWS forecaster must impart as much pertinent information as possible to his customer and, because of this, it is imperative that procedures like those discussed here are not overlooked. Indeed, an analysis of this type is an excellent vehicle to further enhance AWS-customer relationships since it requires strong interaction between AWS personnel and user agencies. Active user participation in this type of analysis is a prerequisite to obtaining meaningful results. (This requirement has been repeatedly stressed by Huschke [6] in establishing guidelines for studies of this type.)

II. The Concept.

In actuality, most, if not all, inputs to a decision are uncertain; it is the degree and quantification of this uncertainty that provides useful information to the decision-maker. Furthermore, measurements of uncertainties must be in terms that the operational decision-maker can easily understand and use.

In evaluating the effectiveness of meteorological information, the principal uncertainty must necessarily be the meteorological information itself and the task of quantifying that information belongs to the meteorological community.

With this in mind, the basic concept is to model various operational environments with weather conditions or parameters as the sole inhibiting factor (in a "simple" model). It must be assumed at the outset that decisions regarding other variables within the problem are

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correct. Thus, the end result is a true measure of the contribution of meteorological information.

A simple model will adequately serve to exemplify the uses and also the importance of a decision theory approach. Rather than use an actual operational situation, it was considered more feasible to contrive a simple, but somewhat realistic, situation for illustrative purposes. Even so, the meteorological data used in this model were obtained from actual climatological records.

III. The Procedure

The basic methodology employed in the ensuing decision-model is that espoused in a book on decision theory by Chernoff and Moses [7]. By combining conditional probabilities, climatological probabilities, and operational loss values for specified actions in the manner to be described below, one can obtain "optimum" operational strategies. Conditional probabilities comprise the "experimental matrix". This matrix contains probabilities that a particular forecast category (F,) for some methorological variable will have been forecast, given that a particular observational category $(\boldsymbol{\theta}_i)$ occurs. These probabilities are represented in the text by $P(F_k | \theta_i)$. Climatological probabilities, collectively termed the "climatology vector", represent the probabilities of occurrence of the observational categories based on past records. These probabilities are represented in the text by $P(\theta_i)$. The "loss table" contains operational costs incurred for particular actions (A_i) when specified observational categories occur. These values are represented by $L(\theta_i, A_j)$. All of the above values are combined to obtain expected (long-run average) losses by observational category, $L(\theta_i, S_g)$, and, subsequently, the expected loss for each of the possible strategies, $L(S_0)$. The strategy which is operationally feasible and shows the minimum loss is then selected as the optimum strategy. In this case, a strategy is defined as a vector (Sg) composed of the actions taken corresponding to each forecast category. Thus, $S_q = (A_j(F_1), A_j(F_2), \dots, A_j(F_r))$. S_q is equivalent to "action order" in the attached computer program. For the above variables, the subscript limits are as follows: $i = 1, \ldots, m; \neq 1, \ldots, n; k = 1, \ldots, r; q = 1, \ldots, t.$ A symbolic and conceptual representation of the above decision-model is shown in Figure 1. The actual procedure for computing the $L(S_{\alpha})$ is discussed below.

In many instances the use of a computer would be necessary for computing the $L(S_q)$ since many strategies can result from having only a few forecast categories and a few actions. The total number of possible strategies for a given problem is equal to the number of possible actions raised to a power equaling the number of forecast categories. Thus, if there are 4 possible actions and 3 forecast categories, there are 4° or 6° 4 strategies that must be simulated. If a computer is used to calculate the losses, large numbers of strategies can be examined.

In their study Chernoff and Moses [7] approach the decision problem in several ways. The technique presented in this technical note is but one of their methods, however, it is felt to be an extremely useful one. Even so, more investigation into the field of decision theory must be accomplished before the best method can be determined for each specific type of problem. Elaboration on the method chosen for this study follows.

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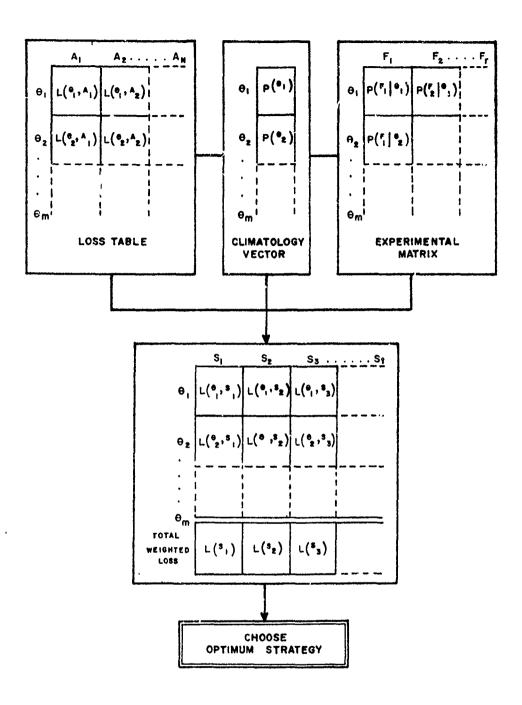


Figure 1
Symbolic and Conceptual Representation
of
Decision Model

given problem. The procedure takes into consideration the cost of taking specified actions under specified observational categories and the probabilities associated with the occurrence of the observational categories and the forecast categories. The first procedural step to compute the expected loss for a given strategy, S_q , is to determine the conditional probability for each action with respect to each observational category, $P(A_j | \mathbf{e}_i)$. This is done by summing the conditional probabilities for each occurrence of a particular A_j in the strategy vector, S_q . Probabilities of occurrence for each action are thus obtained for each observational category. The second step is to multiply the loss value for each action/observational-category combination by the respective action-probability-of-occurrence value obtained in the first step. The third step is to multiply each result from the second step by the appropriate observational-category-probability-of-occurrence value (climatological probability). The final s_i is to sum the results of the third step to obtain the expected value of the loss that would result if S_q were implemented. (The above procedure is presented in symbolic fashion in Figure 2.) This procedure is subsequently followed for each S_q , whereupon that strategy which is feasible and has the minimum expected loss is selected as the optimum strategy.

STEP 1: Compute
$$P_q(A_j | \theta_1)$$
 for all i's and j's;

where $P_q(A_j | \theta_1) = \sum_{k=1}^r P(F_p | \theta_1) = \begin{bmatrix} A_h(F_k) \\ A_h(F_k) \end{bmatrix}$

with
$$\begin{cases} J=1 & \text{if } h=j \\ J=0 & \text{if } h=j \end{cases}$$

where $\mathbf{A}_{\mathbf{h}}$ is that action taken where $\mathbf{F}_{\mathbf{k}}$ is given for

Strategy Vector Sq.

STEP 2: Compute
$$L(\theta_i, A_j)$$
 $P_q(A_j | \theta_i)$ for all 1's and j's

STEP 3: Compute
$$L(\theta_1, S_q)$$
 for all 1's and j's;
where $L(\theta_1, S_q) = P(\hat{y}_1) L(\theta_1, A_j) P_q(A_1 | \theta_1)$

STEP 4: Compute
$$L(S_q)$$
;

where $L(S_q) = \sum_{i=1}^{m} L(\theta_i, S_q)$

$$= \sum_{i=1}^{m} \sum_{j=1}^{n} P(\theta_i) L(\theta_i, A_j) P_q(A_j | \theta_i)$$

Figure 2

Procedure for Computing Expected Loss for Strategy S_q

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The above technique is best illustrated in the use of a simple, but somewhat realistic, operational-decision problem. First, a coenario for the problem is presented, followed by a listing of the operational and environmental data used for the problem. A dry-run will then be performed on two of the strategies to illustrate the above procedure. Following this, a description of a computer program which applies the above principles will be presented.

IV. Scenario and Dry-Run.

The scenario will consist of a logistical mission to resupply Base Y. Aircraft are to depart from Base X with the intention of resupplying Base Y. The surface visibility at Base X is considered to be the critical factor in determining whether or not the aircraft should depart for Base Y. Weather at Base Y is assumed to be good in this simplified nodel (in other words, weather at Base Y is not considered to be a significant factor in the mission completion, e.g., supplies can be paradropped into Base Y). The aircraft may rely on only 06Z and 12Z forecasts of visibility for Base X (made at 00Z and 06Z, respectively). The observation times are also 06Z and 12Z. The forecast and observational categories also include the same visibility intervals(≥ 3 miles, ≤ 3 miles). It is risky for the aircraft to take off when the visibility is less than 3 miles. In addition, the planes must depart at either 06Z or 12Z. There are three possible actions that can be taken as a result of a particular forecast. These actions are as follows: $A_1 = \text{takeoff} -- \text{requires 2 hours preparation time prior to departure; } A_2 = \text{cancel mission } -- \text{i.e., mission failure; } A_3 = \text{delay 6 hours.}$

Operational category $\theta_j = < 3$ miles occurs). Finally, a loss of 20 units is incurred for failing to complete the mission (this value may be a quantification of the need for supplies at Base Y).

Figure 3 contains the loss table, climatology vector, and the experimental matrix for the sample problem. For this example, the experimental matrix has been constructed using a persistence forecast (i.e., persistence probability values were used to construct the matrix). The loss table was determined in a somewhat subjective manner by the authors, and assumes that the decision-maker will follow the chosen strategy regardless of the consequences. Remember, the object is to pick that strategy which will result in the lowest long-run average loss. The best strategy may backfire on occasion, but it should do so less often than the other possible strategies. The climatology vector and the experimental matrix arc, or have been derived from, real data. The loss table was constructed by summing the possible losses according to the criteria cited in the previous paragraph with respect to the possible combinations of action and observational category. For example, if the observational category is < 3 miles, and the action implemented is a takeoff, considerable cost could be incurred. There will be a loss of 4 units for 2 hours of preparation time. There will also be a 5-unit loss for making a wrong decision, and a 20-unit loss for failing to complete the mission.

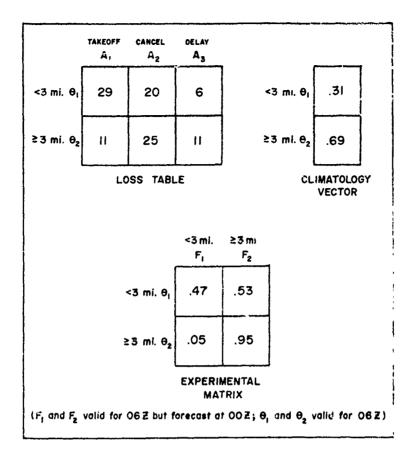


Figure 3. Data for Sample Problems

Thus, the total loss for this combination of action and observational category is 29 units.

The set of tables and data shown in Figure 3 is valid for the 00Z decision time (i.e., a decision as to the action to be taken is made as a result of the forecast issued at 00Z. An extension of the model would be to recycle the procedures stated above in conjunction with a new set of data for the 06Z decision time as would be required in the case of a "delay" action from the first cycle. The method of combining costs for the two decision periods, in the case of a delay from the first period, may seem obvious at first glance but further consideration reveals this not to be true. Since it is not clear to the authors how to best combine the two sets of data to obtain viable results, this Note contains an exposition of the procedure and results when dealing with one cycle only.

Given the above data and assumptions, a dry run will now so undertaken for the first and eighth strategies in this example to illustrate the technique more clearly. Since, in this problem, there are three actions and two forecast categories, we have 3^2 or 9 possible strategies. By performing an ordered permutation, it can be seen that $S_1 = (A_1, A_1)$ and $S_8 = (A_3, A_2)$. According to the procedure outlined above, these strategies can be represented as follows:

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$$\begin{split} \mathbf{L}(\mathbf{S}_{1}) &= \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{S}_{1}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{S}_{1}) \\ &= \mathbf{P}(\mathbf{\theta}_{1}) \ [\mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{1})\mathbf{P}_{1} \ (\mathbf{A}_{1}|\mathbf{\theta}_{1}) + \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{2})\mathbf{P}_{1} \ (\mathbf{A}_{2}|\mathbf{\theta}_{1}) + \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{3})\mathbf{P}_{1} \ (\mathbf{A}_{3}|\mathbf{\theta}_{1})] + \\ &\quad \mathbf{P}(\mathbf{\theta}_{2}) \ [\mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{1})\mathbf{P}_{1} \ (\mathbf{A}_{1}|\mathbf{\theta}_{2}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{2})\mathbf{P}_{1} \ (\mathbf{A}_{2}|\mathbf{\theta}_{2}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{3})\mathbf{P}_{1} \ (\mathbf{A}_{3}|\mathbf{\theta}_{2})] \\ &\quad \mathbf{L}(\mathbf{S}_{8}) &= \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{S}_{8}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{S}_{8}) \\ &= \mathbf{P}(\mathbf{\theta}_{1}) \ [\mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{1})\mathbf{P}_{8} \ (\mathbf{A}_{1}|\mathbf{\theta}_{1}) + \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{2})\mathbf{P}_{8} \ (\mathbf{A}_{2}|\mathbf{\theta}_{1}) + \mathbf{L}(\mathbf{\theta}_{1}, \ \mathbf{A}_{3})\mathbf{P}_{8} \ (\mathbf{A}_{3}|\mathbf{\theta}_{1})] + \\ &\quad \mathbf{P}(\mathbf{\theta}_{2}) \ [\mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{1})\mathbf{P}_{8} \ (\mathbf{A}_{1}|\mathbf{\theta}_{2}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{2})\mathbf{P}_{8} \ (\mathbf{A}_{2}|\mathbf{\theta}_{2}) + \mathbf{L}(\mathbf{\theta}_{2}, \ \mathbf{A}_{3})\mathbf{P}_{8} \ (\mathbf{A}_{3}|\mathbf{\theta}_{2})] \end{split}$$

Referring to Figure 3 and the above equations, $L(S_1)$ and $L(S_8)$ can be computed as follows:

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$$L(S_1) = .31 \times [29x1 + 20x0 + 6x0] + .69 \times [11x1 + 25x0 + 11x0] = 16.58 \text{ units}$$

 $L(S_0) = .31 \times [29x0 + 20x.53 + 6x .47] + .69x[11x0 + 25x.95 + 11x.05] = 20.93 \text{ units}$

Each of the other strategies is computed in the same manner with the lowest cost, operationally-feasible strategy being selected as the optimum.

V. Computer Program.

VI. Conclusion.

As mentioned previously, a computer program has been written which performs the above calculations. The program is written in FORTKAN IV for use by personnel not especially program-oriented. It was designed and programmed on a DEC PDP-10 which was accessed in a time-sharing mode using a Teletype 33 terminal. The program operates in a "conversational" status, in that it allows the user to "converse" with the program as to how the program works, what data are required for input, what options are available, and what type of output is available. A complete listing of the program, including appropriate documentation is contained in Attachment 1. A sample execution run of the program is contained in Attachment 2.

This program could provide operations or planning personnel with the capability of obtaining pertinent decision-making information in a short period of time, provided the computer capability is readily available. If the program were implemented in conjunction with a cathode ray tube (CRT) display terminal, even faster response and greater effectiveness of the decision-making tool could be realized. The present program is capable of handling up to 3,125 strategies (56), but could be easily expanded to include more meteorological variables and more diversified actions; thus, providing the user with greater flexibility. However, the run times and other costs for enhancements of this type are definitely increased and a cost/benefit analysia would have to be performed to determine the feasibility of the more complicated models. For example, a problem that contains 10 possible actions and 6 forecast categories would require that 1,000,000 scrategies be simulated, which could run a considerable length of time, depending on the type of computer hardware used.

The concept of combining the operational and meteorological information is the important factor considered in this study. The specific decision-theory approach presented here may or

may not be the best way to go. It is, however, a step toward the ultimate goal of minimizing loss of resources over the long-run. There is a definite need for more study in this area of improving operational decision-making through the interaction of environmental and operational factors.

VII. References

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² Atch

^{1,} Program Listing

^{2.} Sample Run

C

C

YES

C

```
THIS PROGRAM WILL COMPUTE LONG-FUN MINIMUM AVERAGE LOSSES FOR
  SPECIFIC OPEPATIONAL STRATEGRES, BASED ON OPERATIONAL LOSS VALUES &
   WEATHER OCCUPRENCE PROBABILITIES.
                                   THE INPUT/GUTPUT FOCUMENTATION IS
   PRESENTED IN THE PROGRAM EXECUTION PHASE AND IS GEAPED EITHER TO THE
   EXPERIENCED OR NON-EXPERIENCED USER OF THIS PROGRAMA AS APPROPRIATE.
.C
   LOGIC DOCUMENTATION FOLLOWS. FOR ASSOCIATED INFORMATION REFER TO
   FILES IN THE SPECIAL PROJECTS SECTION.
                                            PETER HALL/JUNE 29,1972
  ACNLOS - TEMPORARY STORAGE FOR THE LOSSES BY ACTION
   AGAÍN - STORÉS À LYÉS! OR LNO! , FOR RECYCLE OF EXECUTION
    ÁPRIOR - A PRIORÍ (CLIMATOLOGICAL) PROBABILITY ARRAY
   EXPNCE - STORES A TYEST OR THOUSE TO SEE WHETHER EXPERIENCED.
   EXPTAE - EXPERIMENTAL TABLE ARRAY FOR CONDITIONAL PROBABILITIES
C
C
          - DO-LOOP COUNTER AND INDEX
    IFORMT - ALPHANUMERIC ARRAY FOR STORING VARIABLE FORMATS
    IGBACN - ARRAY THAT STORES ACTION ORDER FOR EACH STRATEGY
C
          - DO-LOOP COUNTER AND INDEX
   KEOPMT - ARRAY FOR STORING IFORMT (VARIABLE FORMAT) BEING USED
C
C
   LOSTÁB - LOSS TABLE ARRAY
    MINSRT - STRATEGY NUMBER ARRAY WHEN ASK FOR SORTED OUTPUT
C
C
          - DO-LOOP COUNTER AND INDEX, USED IN SORT ROUTINE
    NACTOR - NUMBER OF ACTIONS IN PROBLEM
C
    NERACH - ACTION NUMBER INDEX
C
   NEROUT - NUMBER OF SORTED STRATEGIES TO BE SORTED AND LISTED
C
          - DO-LOOP COUNTER AND INDEX, USED IN SORT ROUTINE
C
   NM
C
          - DO-LOOP COUNTER AND INDEX FOR NUMBER OF FORECAST
   110
C
            CATEGORIES
    NOSKWO - INDEX THAT REVERSES ORDER OF IDSACH ARRAY
C
¢
          - NUMBER OF FÖRECAST CATEGORIES IN PROBLEM
   NOSS
          - DO-LOOP COUNTER AND INDEX FOR NUMBER OF OBSERVATION
C
    NS
            CATEGORIES
    NSTATE - NUMBER OF OBSERVATION CATEGORIES IN PROBLEM
    NETRAT - NUMBER OF STRATEGIES POSSIBLE. IN PROBLEM
          - DO-LOOP COUNTER AND INDEX USED TO STORE A FORMAT STATEMENT
    MrJ
            IN KEORMT
    SORTED - STORES A TYEST OR THOS FOR SORTING STRATEGIES BY LOSS
C
    STALOS - ARRAY FOR CUMULATIVE LOSS IN OBSERVATION CATEGORY
    STRLOS - ARRAY FOR UNSORTED STRATEGY LOSSES
C
C
    STREAT - APPAY FOR SORTED STRATEGY LOSSES
```

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- ALPHANUMERIC TYEST FOR TESTING ANSWERS TO PUESTIONS

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REAL LOSTAS
     MIMÉNISTUM LOSTABOTISHISH PTABOTISHI OBACNOTISTAL OBOS
     PIMENSLEW (中) JOTEL OS (31250 JS TRSRT (50) JMINSPT(50)
     DIMENSION IFORNICE AND KEORMICE)
     DATA IFORNT/54°22X335413312354X32°135543743474453°27 3
                 54(204),ÄHI3,,12,FHX,,ZI1,,5H,,6X)F,ÄH6,02) ,
                 FH(20X) 5H13 5113 FHX 5 411 5H 36 Y 3F 3 5H6 0 2) 3
                 5H.029Y.JFH15J11J5HXJ5T1J5HJ6XJFJ5H6027/ //
     DATA YESZTHYESZ
 ***** REMARKSJEXPLANATION, AND QUESTIONS FOR INPUT.
     TYPE 1001
1001 FORMAT (101)20%) ***** SAYES STRATEGIES ******//OARE YOU!)
            ! F<PERIENCEC? (YES OF NO)!//)</pre>
     ACCEPT 1002, FXPNCE
1002 FORMAT (AZ)
     IF (EXPNOF-EQ-YES) GO TO TO
     T-YPE 1:000-
1000 FORMAT (101,5x, THIS PROGRAM WILL COMPUTE LONG-RUM MINIMUM AVER),
    1 MAGE LUSSES FOR 1/1 SPECIFIC OPERATIONAL STRATEGIES ("BAYES STR")
   >> TATEGIES") BASED ON OPERA-T/T TOTONAL LOSS VALUES AND WEATHER™
    3 ! OCCURRENCE PROFACTLITIES. THE INSUTI/! PARAMETERS ARE AS!
     I FOLLOWS: (1) THE NUMBER OF ACTIONS AVAILABLE, 1/1 (2) THE NUM!,
     THER OF OBSERVATION CATEGORIES USED; (3) THE NUMBER OF ! FORE!
      'CAST CATEGORIES USED, (") THE OPERATIONAL COST (LOSS) FOR!
    7 | EACHI/! COMBINATION OF ACTIONS AND OBSERVATION CATEGORIES, 1)
    8 1 (5) THE CLIMATOLOGY / ICAL PROBABILITY OF OCCURRENCE OF 1)
     I EACH OPSERVATION CATEGORY, ANDIZ ! (6) THE COMPUTIONAL PROBAT.
    A BILITY FOR EACH COMPINATION OF OBSERVATIONIA! AND FORECAST CALL
     ITEGORIES CLOSO, THE PROPABILITY THAT A PARTICULAR FORE-1/1 CAL)
    21ST WAS ISSUED GIVEN THAT A PARTICULAR CREERVATION CATEGORY!/
                           THE INPUT FORMATS ARE AS FOLLOWS: (1), (21)
    3 1 0CC URRED) 01//1
    4 1), AND (3) SHOULD REIVE BYPED AS ONE DIGIT INTERERS; (4), (5)1,
    E 1, AND (6) SHOULD BE TYPED ASI/! THREE DIGIT REAL NUMBERS (INC.),
    6 ILUDING CECIMAL POINT INSERTED ASI/! APPROFRIATE---0, 1, 214
    7 10 OR 3 PIGITS TO THE RIGHT OF THE POINT) 1/1 TYPE CARRIAGE RIGH
    8 METURN AFTER TYPING FACH INPUT VALUE. THE MAXIMUMIZE NUMBER ATA
    9 'LLGWED FOR EACH OF (1), (2), AND (3) IS "5". 1/)
     TYPE 1999
1959 FORMAT(101,5%, OUTPUT COMMENTS: THE ACTION ORDER IS A SEQUENCE !.
    1'OF NUMBERS TO BEI/! INTERPRETED AS FOLLOWS: THE NUMBER IN THE '>
    2'LEFTMOST POSITION OF THE ! / SEQUENCE REPRESENTS THAT ACTION !.
    31TO BE TOKEN IF THE FIRST FORECASTIVE CATEGORY IS FORECAST.
    4 THE NUMBER IN THE POSITION IMMEDIATELY TO THE !/ RIGHT OF **
    FITHE FIRST POSITION IN THE STOUENCE REPRESENTS THAT ACTION!/
    6' TO RE TAKEN IF THE SECOND FORECAST CATEGORY IS FORECAST; 1.
    7'AND SO'/' ON, UNTIL THE NUMBER IN THE RIGHTMOST POSITION OF ',
    SITHE SEQUENCE!/! REFRESENTS THAT ACTION TO SE TAKEN IF THE ..
    SILAST FORFCAST CATEGORY!/! IS FORFCAST. THE ACTION ORDER !>
    1'THUS BECOMES A STRATEGY (I.E., A'/ SET OF DECISION RULES) 🕩
    2 FOR THE DECISION-MAKER. 1)
     TYPE 1003
```

```
1003 FORMAT ( TOROTS OF RUCK | | | 1 / / / )
   50 TYPE 1004
 1004 FORMAT (JONO. OF ACTIONS =1/)
      ACCEPT 1005, NACTHS
 1005 FORMAT (I1)
      TYPE 1010
 1010 FORMAT (!ONO. OF DBS CATEGORIES = 5//)
      ACCEPT 1015, NSTATE
 1015 FORMAT (11)
      TYPE 1020
1020 FORMAT ('ONO, OF FOST CATEGORIES = 1/)
      ACCEPT 1025, NOBS
 1025 FORMAT (I1)
      TYPE 1040
4040 FORMAT (!OLOSSES (INCLUDE DECIMAL POINT):!/)
      DO 1 I=1,NSTATE
      DO 1 J=1 NACTNS
      TYPE 1044, I,J
 1044 FORMAT (10(1)11)1)1711)1 =177
      ACCEPT 1045, LOSTAB(I)J)
 1045 FORMAT (F4.2)
    1 CONTINUE
      TYPE 1030
 1070 FORMAT ( OCLIME PROBABILITIES: 1/)
      DO T I=1, NSTATE
      TYPE 1034,1
 1034 FORMAT (10(1)11)1) =1/)
      ACCEPT 1035, APRICR(I)
 1075 FORMAT (F462)
    3 CONTINUE
      TYPE 1050
 1050 FORMAT CROCONDITIONAL PROBABILITIES W//
     .00 2 I=13NSTATE
      DO 2 3=1, NOBS
      TYPE 1054, I,J
 10^{\circ}4 FORMAT (%0(1)11)1)11(1) = 1/)
      (U(I) BATTAR (2301 THRODA
 1055 FORMAT (F4a2)
    2 CONTINUE
C **** LOADING REQUIRED FORMAT LINE BASED ON THE NUMBER OF FORECAST
C **** CATEGORIES.
      DO 45 NWD=1.5 1.
      KFORMT (NVD) = IF ORMT (NVP)NOPS-1)
   45 CONTINUE
      C=MM
C **** COMPUTING THE NUMBER OF STRATEGIES.
```

STRSRT(N)=STRLOS(NER)

MINSPT(N)=NSR

```
NSTRAT=NACTNS**NOPS
  MPROUT=NSTRAT
 ***** QUESTIONS AND INPUT TO CETEPMINE IF SORTED OUTPUT IS DESIRED.
 ***** AND IF SO HOW MANY STRATEGIES ARE TO BE SORTED.
   4 TYPE 1075
1075 FORMAT (1000 YOU WANT THE STRATEGIES SORTED BY LOSS, AND LISTED!,
             " IN ASCENDENCY!
                                    ORDER? (YES OR NO)!/
     ACCEPT 10PO, SORTED
10PO FORMAT (A#)
     IF (SORTED-NE-YES) GO TO 44
     TYPE 1085
1085 FORMAT CICHON MANY STRATEGIES WOULD YOU LIKE LISTED2//
                    (2-DIGIT INTEGER--MAX IS FO)*/)
     ACCEPT 1090, NBROUT
10°0 FORNAT (12)
 ***** COMPUTING STRATEGY LUSS VALUES USING PAYESIAN APPROACH.
       FOR DETAILED EXPLANATION OF THE BAYESIAN METHOD REFER TO
  ***** "ELEMENTARY DECISION THEORY" BY CHERNOFF AND MOSES (CHAPTERS 1
 ***** AND 6): PUBLISHED BY WILEY, COPYRIGHT 1959.
  44 DO 10 NER=1.NSTRAT
     CALL ACHORD (NBR)NORS, NACTHS, IOBACHD
    . DO 20 NS=1.NSTATE
     20 30 NO=1.NOPS
     NOBK WD = N 0 P3 - N 0 + 1
     NBRACN=10PACN(NOPYWG)
     ACNLOS=EXFTAP(NS)NOO*LOSTAB(NS)NBRACN)
     STALOS(NS)=STALOS(NS)+ACNLOS
  30 CONTINUE
     STAL CS (NS)=STAL GS(NS)*APRIOR(NS)
     STRLOS (NBR) #STRLOS (NBR) + STALOS (NB)
  20 CONTINUE
      IF (SORTED NE YES) GO TO 21
 ***** 9561NNING OF "PUSHPOWN" SORT FOR SORTED OUTPUT.
     DO 23 N=13NBROUT
     IF (STRLOS(N3R).LF.STRSRT(N)) GO TO 26
     IF (STRSPT(N).NE.O.) 00 TC 23
     STRSRT(N)=STRLOS(NJR)
     MINSRT(N)=NBR
     GO TO 21
  23 CONTINUE
     50 TO 21
  26 DO 27 NN=NOROUT,N+1,-1
     STRSRT(NN)=STRSRT(NN-1)
     MINSTICNN) =MINSET(NN-1)
  27 CONTINUE
```

```
** RESETTING LOSSESJEY OF SERVATION CATEGORY JTO ZERVA
   21 DO 25 NS=1,NSTATE
      STALDS (NS)=0.
   25 CONTINUE
   10 CONTINUE
   **** TYPING OUTPUT HEADINGS.
      TYPE 1060
1060 FORMAT (101)27x, 1PAYES STRATEGIES!//20x, 1STRATEGY 1,7x, 1ACTION 1,7x,
              ILOSSIN21X, INUMBERT, 84, IORDERINA)
      IF (SORTED . ER . YES) GO TO 90
  **** NON-SORTED OUTPUT ROUTINE
      DO 40 I=1,NSTPAT
      NER=I
     CALL ACHOPO CNBRONGESONACTNSOTOPACADA
      TYPE KFORMT, NBR, (IOTACN (NOBKHD), NOBKHD=NOBS, 1,-1), STREOS(I)
   40. CONTINUE
      90 TO 95
  **** SORTED OUTPUT'ROUTINE
   CO DO 41 I=1,NSROUT
      NRR=MINSRT(I)
      CALL ACHORD (NBR, NOES, NACTHS, IOBACN)
      TYPE KFORMT, NBR, (IORACN(NORKWD),NORKWD=NOBS,1,-1),STRSPT(I)
   41 CONTINUE
¢
  ***** QUESTIONING AS TO WHETHER USER WOULD LIKE ANOTHER TRY AT
C
   95 TYPE 1065
 1065 FORMAT ( ONOULD YOU LIKE TO TRY AGAINT (YES OP NO) !/)
      ACCEPT 1070, AGAIN
 1979 FORMAT (AF)
      IF (AGAIN NE YES) STOP
       ZERDING OUT ARRAYS FOR ANOTHER TRY.
C.
C
      00 64 I=1,N09S
      I 03ACN(I)=0
   44 CONTINUE
      DO 65 I=19NSTATE
      STALOS(I)=0.
      APRIOR (I)=00.
      DO 65 J=1,NO3S
      LOSTAR(I)J)=0.
      FXPTAS(I)=0
```

```
66 CONTINUE
    DO 67 I=13NSTRAT.
    STRLOS(I)=ů.
 67 CONTINUE
    IF (SORTEBONE YES) OF TO 68
    TO 68 I=40NBROUT
    STRSRT(I)=0.
  . MINSRT(I)=0.
 F8 CONTINUE
    GO TO 50
    END
           4.5. 新芦苇科·沙葵 新新叶芦芦芹菜 新茶 芳秋 · ACNORO · 西提伊萨 新茶种 新茶 新菜 新菜 新花 新花 新菜 新菜 新菜 美国
      THIS SUBROUTINE COMPUTES THE ACTION ORDER FOR FACH STRATEGY
NUMBER AS REQUIRED. PARAMETERS (IN ORDER) ARE: STRATEGY NUMBER.
NUMBER OF FORECAST CATEGORIES. NUMBER OF ACTIONS FOR INCUTS AND
**CTTON ORDER ARRAY FOR OUTPUTA
йййнийний 1900 ТИГРОО — инийнийнийнийнийнийнийнийнийний
 CHEDIVIO - ONTIVO
 MCPACH - ACTION ORDER APRAY
 ICUOT - QUOTIENT
         - DO-LOOP COUNTER AND INDEX
 NACTHS - NUMBER OF ACTIONS
 NED
         - STRATEGY NUMBER
         - NUMBER OF FORECAST CATEGORIES
 NOBS
           **************PROGRAM LISTING *****
   SUBROUTINF ACTION (NRR, NORS, NACTNS, 109ACM)
   INTEGER DVIDNO
   DIMENSION IORACN(NOES)
   IQUOT=NBP-1
   00 10 J=4.N03S
   "VIOND = I QUOT.
   IF (IQUOT.EQ.0) GC TO 9
   IOUCT=DVICND/NACTES
 9 IOBACN(J)=DVIDND-NACTNS*IQUOT+1
10 CONTINUE
   CETURN
   END
```

ARE YOU EXPERIENCED? (YES OP NO)

NO

THIS PROGRAM WILL COMPUTE LONG-RUN MINIMUM AVERAGE LOSSES FOR SPECIFIC OPERATIONAL STRATEGIES ("BAYES STRATEGIES") BASED ON OPERATIONAL LOSS VALUES AND MEATHER OCCURRENCE PROBABILITIES. THE INPUT PARAMETERS ARE AS FOLLOWS: (1) THE NUMBER OF ACTIONS AVAILABLE, (2.): THE NUMBER OF OBSERVATION CATEGORIES USED, (3) THE NUMBER OF FORECAST CATEGORIES USED, (4) THE OPERATIONAL COST (LOSS) FOR FACH COMBINATION OF ACTIONS AND OBSERVATION CATEGORIES, (50) THE CLIMATOLOGICAL PROBABILITY OF OCCURRENCE OF EACH OBSERVATION CATEGORY, AND (6) THE CONDITIONAL PROBABILITY FOR EACH COMBINATION OF OBSERVATION AND FORECAST CATEGORIES (1.0.) THE PROBABILITY THAT A PARTICULAR FORECAST MAS ISSUED GIVEN THAT A PARTICULAR OBSERVATION CATEGORY

THE THRUT FORMATS ARE AS FOLLOWS: (1) (2) AND (3) SHOULD BE TYPED AS ONE DIGIT INTEGERS: (4), (5), AND (6) SHOULD BE TYPED AS THREE DIGIT REAL NUMBERS (INCLUDING DECIMAL POINT INSERTED AS APPROPRIATE---0, 1, 2, OR 3 DIGITS TO THE RIGHT OF THE POINT). TYPE CAPRIAGE RETURN AFTER TYPING EACH INPUT VALUE. THE MAXIMUM NUMPER ALLOWED FOR EACH OF (1), (2), AND (3) IS "E".

CUTPUT COMMENTS: THE ACTION ORDER IS A SEQUENCE OF NUMBERS TO PEINTERPRETED AS FOLLOWS: THE NUMBER IN THE LEFTMOST POSITION OF THE SEQUENCE REPRESENTS THAT ACTION TO BE TAKEN IF THE FIRST FORECAST CAPPORY IS FORECAST. THE NUMBER IN THE POSITION IMMEDIATELY TO THE RIGHT OF THE FIRST POSITION IN THE SEQUENCE REPRESENTS THAT ACTION TO BE TAKEN IF THE SECOND FORECAST CATEGORY IS FORECAST: AND SO ON! UNTIL THE NUMBER IN THE RIGHTMOST POSITION OF THE SEQUENCE REPRESENTS THAT ACTION TO BE TAKEN IF THE LAST FOREGAST CATEGORY IS FORECAST. THE ACTION ORDER THUS BECOMES A STRATESY (1.5.) A SET OF DECISION RULES) FOR THE DECISION-MAKER.

ROTE OF RUCKILL

NU . OF ACTIONS =

NO • OF 03S CATEGORIES =

NG. OF FCST CATEGORIES =

(1:1) = 27.

(1,2) = 20.

(1,7) = 6.

(2:1) = 11.

(2,2) =

(2·33) = 41 n

CLIME PROBABILITIES:

(1) = : •31

(2) = •67

CONDITIONAL PROPABILITIES:

(1,1): = .47

(1)2) = 53

population interpretation interpretation interpretation

(2)1) = 005

(2)?) = 0.9 ^K DO YOU WANT THE STRATEGIES SORTED BY LOSS. AND DISTED IN ASCENDING ORDER? CYPS OR NO.

NO

BAYES STRATERIES

STRATEGY NUMBER	ACTION ORDER	LOŚS
		•
5 1	11	16.059
·••	12	24.28
?	13	12.00
u .	.2.1	1. 375
5	22	28₀45
6	23	11097
7	31	13.23
9	32	20.53
c	32 37	9.45

WOULD YOU LIKE TO TRY AGAIN? (YES OR NO) YES

NO . OF ACTIONS =

NO. OF CBS CATEGORIES =

NO. OF FOST CATEGORIES ==

LOSSES (INCLUDE DECIMAL POINT):

(1,1) = 29.

(1.92) = 20.0

(1,3) = 6.

(2,1) = 11.0

```
PAGE 2:3
(2,2) =
25 •
(Ž=)3) =
11.0
CLIME PROBABILITIES:
(1) =
.31
(2) =
069
CONDITIONAL PROPABILITIES
(1,1) =
•47
(1)?) =
.5.7
(2,1) =
.05
(2)?) =
.95
DO YOU WANT THE STRATEGIES SORTED BY LOSS, AND LISTED IN ASCENDING
     ORDER? (YES OR NO)
YES
HOW MANY STRATEGIES WOULD YOU LIKE LISTED?
     (2-DIGIT INTEGER -- MAX IS 50)
9
```

STRATEGY	ACTION	LUSS
NUMFER	OPDER	
	_	_ 2
c	33	9045
б	23	11.97
7	13	12.80
7	31	17.23
<i>t</i> i	21	15.75
1	11	16.5R
Þ	32	20.53
- ⊼	22	34.944
2	12	24.29

WOULD YOU LIKE TO TRY AGAIN? (YES OF NO) NO

CRU TIME: 7.96 ELAPSED TIME: 5:33.00 NO FXECUTION ERRORS DETECTED

EXIT.

REPORT TITLE In Operational Decision Model Employing Operational and Environmental Factor Descriptive Notes (Type of report and inclusive dates) Author(s) (First name, middle initial; last name) Lt Dana P. Hall REPORT DATE November 1972 CONTRACT OR GRANT NO. PROJECT NO. Se. OTHER REPORT NO(s) (Any other numbers that mathic report)	CATION
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Hq Air Weather Service (MAC) Scott AFB, IL 62225	
II. ABSTRACT	
The model discussed in this Note combines conditional climatological pr	·chahdi 1+4
in the model the second of the second	ODAUTITUE
climatological probabilities, and operational loss values for specified acti	Ous in a
manner to make the best operational decision. A sample scenario is given an	a demon-
strated using a hypothetical problem of airlift supply.	
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FORM 1473 DD

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LIST OF USAFETAC TECHNICAL NOTES

Number	<u>Title</u>	Date
71-1	Interim Instructions for the Use of the National Meteorological Center Air Pollution (APP) Products (AWS distribution only) (AD-718966)	Feb 71
71-2	A Reprint of Use of FOUS (Detailed PE Guidance) (AWS_distribution only). (AD-719866)	Mar 71
71-3	Superseded by USAFETAC TN 72-3	
71- 4	Diurnal Variation of Summertime Thunderstorm Activity over the United States (AD-724645)	Apr. 71
71-5	Preliminary Verification of AFGWC Boundary-Layer and Macroscale Cloud-Forecasting Models (AD-725738)	Jun.:71
71-6	Use of Extrapolation in Short-Range Forecasting (AD-729022)	Sep 71
71-7 ,	Glossary of Spanish, French, German, English Selected Climatological and Meteorological Terms (AD-731554)	Aug 71
71_8	A Prediction Method for Blast Focusing (AD-732765)	Sep 71
71- 9	Determination of Maximum Emission Rates to Meet Air Quality Standards (AD-733505)	Aug 71
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72-4	A Selected Annotated Bibliography on the Tropopause (AD-738594)	Feb 72
7 2 - 5	A Selected Annotated Bibliography of Environmental Studies of Italy (1952-1971) (AD-741806)	May 72
72 - 6	An Investigation into the Proper Spatial and Temporal Frequency of the Meteorological Rocketsonde Network (AD-744824)	Jun 72
72-7	Random Error Variance and Covariance Estimates from Simultaneous Radar (FPS-16) Measurements (AD-)	Sep 72
72-8	An Operational Decision Model Employing Operational and Environmental Factors (AD-	Nov 7,2